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Question Paper Code: Q 2765

B.E./B.Toch. DEGREE EXAMINATION, NOVEMBER/DECEMBER 2009.

Seventh Semester

Electrical and Electronics Engineering

EE 1001 — SPECIAL ELECTRICAL MACHINES

(Common to B.E. (Part-Time) Sixth Semester Regulation 2005)

(Regulation 2004)

Time: Three hours

Maximum: 100 marks

Answer ALL question

PART A - $(10 \times 2 = 20 \text{ ma. ks})$

- 1. What are the types of rotor available in "no hronous reluctance motor?
- 2. What is vernier motor?
- 3. Give the classification of stepres motor.
- 4. Define the term skewing
- Draw the speed torque characteristics of switched reluctance motor.
- 6. List any four applications of switched reluctance motor.
- 7. What are the advantages of PMBL DC motor?
- 8. Give the ression for the emf and torque of a PMBL DC motor.
- 9. What is load commutation?
- 10. What is the magnitude of stator current in PMSM to achieve demagnetization?

PART B — $(5 \times 16 = 80 \text{ marks})$

11. (a) Explain the principle of operation and constructional features of different

		types of synchronous reluctance motor.
		Or
	(b)	Explain the circle diagram and torque speed characteristics of synchronous reluctance motor.
2.	(a)	(i) Describe the operation of a variable reluctance type stepper motor. (8)
		(ii) Draw and explain the torque pulse rate characteristics of a stepper motor. (8)
1		Or Or
	(b)	(i) Explain the working of hybrid motor with neat tiag am. (10)
		(ii) What is stepping angle? A VR stepper mo or has 8 poles in the stator and they have five teeth in each pole. If the rotor has 50 teeth, calculate the step angle and resolvering. (6)
3.	(a)	Describe the Hysterisis type and PWM concurrent regulator for one phase of a switched reluctance motor with request diagrams.
		Or
	(b)	With neat diagram, explain the missippocessor based control of switched reluctance motor.
1.	(a)	Explain the construction and the ciple of operation of PMBLDC motor with neat diagram.
		Or a remaining the second seco
	(b)	Describe the operation of power controllers for PMBLDC motor with neat diagram.
5.	(a)	Explain the construction and performance of a permanent magnet synchronous rowtor with neat diagram.
		Or Control of the Con
	(b)	Derive the emf and torque equations of permanent magnet synchronous motor.
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		Note that we have a second sec